

Stochastic Models

Epidemiological data

- 3 Main kinds of stochasticity

1. Observation noise

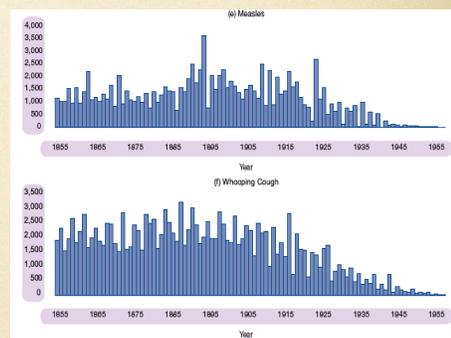
- Likelihood of detecting and reporting a case

2. Environmental noise

- “good” versus “bad” years

3. Demographic noise

- Individual-level chance events



Motivation

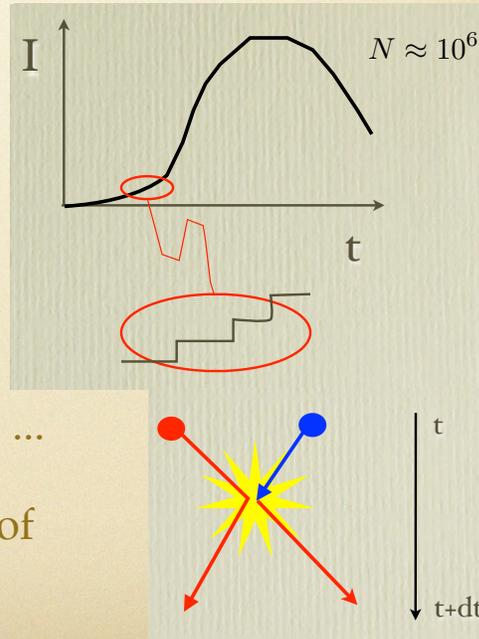
- SIR model

$$\frac{dI}{dt} = \beta X \frac{Y}{N} - \gamma I$$

- Which means

$$dY = \beta X \frac{Y}{N} dt - \gamma Y dt$$

- But, in reality, $dY = 0, 1, 2, \dots$
- Need to consider physics of individuals bumping into each other



Demographic Stochasticity

- Defined as *fluctuations in population processes arising from random nature of events at level of individual*
- Baseline probability associated with each event is fixed, but because of chance events, individuals experience differing fates
- Need to modify ODEs in two ways to incorporate demographic stochasticity:
 - Make state variables integer-valued (X, Y, Z)
 - Introduce transition probabilities
- *Some analytical methods possible*

Demographic Stochasticity

- Analytical approaches involving Master Equation potentially powerful, but often too difficult to implement
- Alternatively, results from 'branching process' theory can be used
- And then, there's always brute-force simulation (which is what we'll start with)

Demographic Stochasticity

- Good news: very straightforward methods exist for exact simulation of these stochastic processes
- To simulate, we need to answer two fundamental questions, starting with a specified system state at time t :
 - When is next event?
 - What is next event?

Deriving time to next event

- Can derive “inter-event” times from fundamental population principles
- Let's assume we have a population of size N at time t , then we define $G_N(s)$ as probability that no event occurs in subsequent time interval of length s . So,

$$G_N(s+\delta s) = \Pr\{\text{no event in time interval } (t, t+s+\delta s)\} \\ = \Pr\{\text{no event in } (t, t+s)\} \times \Pr\{\text{no event in } (t+s, t+s+\delta s)\}$$

- So, substituting $C(N) = \text{sum of frequencies of all events}$, we get

$$G_N(s + \delta s) = G_N(s) \times \{1 - C(N) \times \delta s\}$$

Deriving time to next event

$$G_N(s + \delta s) = G_N(s) \times \{1 - C(N) \times \delta s\}$$

After tidying up and re-arranging:

$$\frac{[G_N(s + \delta s) - G_N(s)]}{\delta s} = -C(N) \times G_N(s)$$

By now, you shouldn't be surprised by what comes next. We let $\delta s \rightarrow 0$, which gives

$$\frac{dG_N}{ds} = -C(N) \times G_N(s)$$

Deriving time to next event

Solution is exponential equation:

$$G_N(s) = e^{-C(N)s}$$

Naturally, probability that next event occurs in $(t, t+s)$ is therefore:

$$F_N(s) = 1 - G_N(s) = 1 - e^{-C(N)s}$$

Note:
independent of
starting time t

So, F_N is exponentially distributed

Deriving time to next event

To simulate a random inter-event time, draw a random number U_1 from a uniform distribution ($1 \geq U_1 \geq 0$) and equate with $F_N(s)$

$$U_1 = F_N(s) = 1 - e^{-C(N)s}$$

Now, solve for s :

$$s = -\frac{\log(U_1)}{C(N)}$$

Can now move on to our exact stochastic simulation algorithm

Demographic Stochasticity

- Many ways to implement such an approach (K&R pp200-205)
- A popular (and mathematically rigorous) method is called Gillespie's Direct Algorithm (Gillespie 1977)

Gillespie's Direct Method

1. Label all possible events E_1, \dots, E_n
2. Calculate rate at which each event occurs R_1, \dots, R_n
3. Rate at which *any* event occurs is $R_{\text{sum}} = \sum_i R_i$
4. Calculate time until next event
$$\delta t = \frac{-1}{R_{\text{sum}}} \log(U_1)$$
5. Generate uniform deviate, U_2 , and set $P = U_2 \times R_{\text{sum}}$
6. Event p occurs if
$$\sum_{m=1}^{p-1} R_m < P \leq \sum_{m=1}^p R_m$$
7. Update state, time $t = t + \delta t$ and return to step 2

Gillespie's Direct Method

- Let's implement this for SIR model, with demography
- Event rates are $\mathbf{R}=(\mu N, \beta XY / N, \mu X, \gamma Y, \mu Y, \mu Z)$
- Sum of event frequencies is

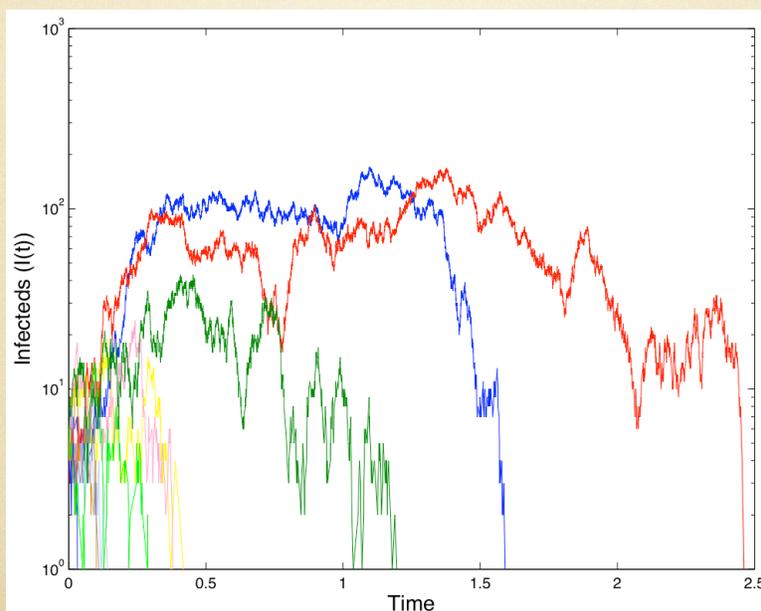
$$R_{sum} = 2 \times \mu N + \beta XY + \gamma Y$$

- Time until next event:

$$\delta t = \frac{-1}{R_{sum}} \log(U_1)$$

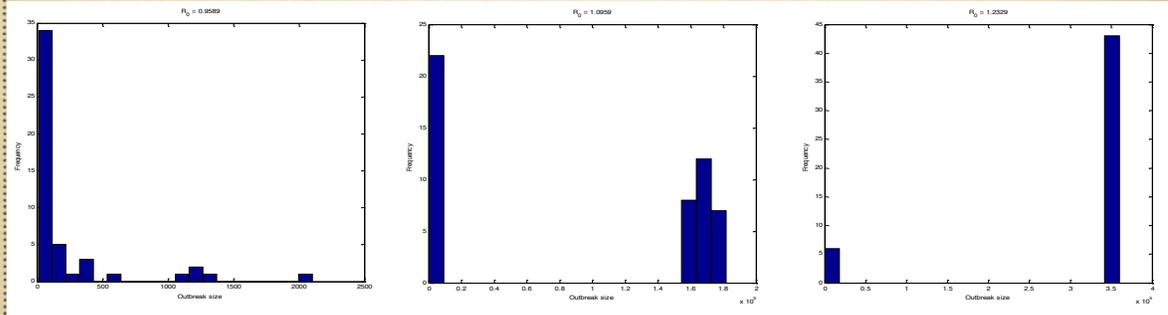
- Set $P = U_2 \times R_{sum}$ and find p $\sum_{m=1}^{p-1} R_m < P \leq \sum_{m=1}^p R_m$
- Update variables, time ($t = t + \delta t$) and repeat

Stochastic Epidemics



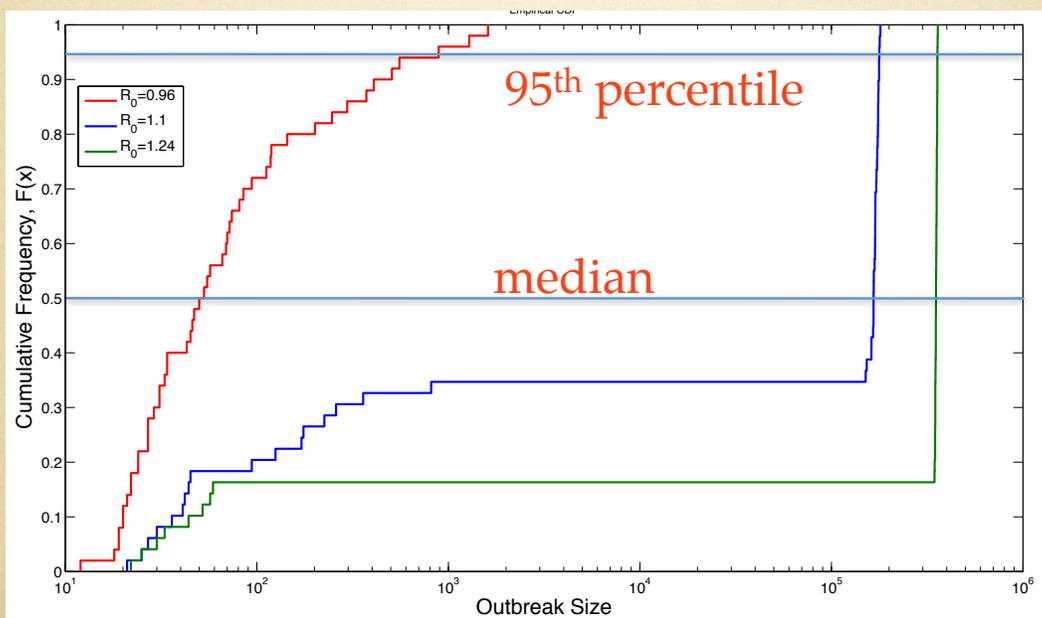
Characterising variability

- Can repeat invasion of pathogen into virgin population a number of times and examine

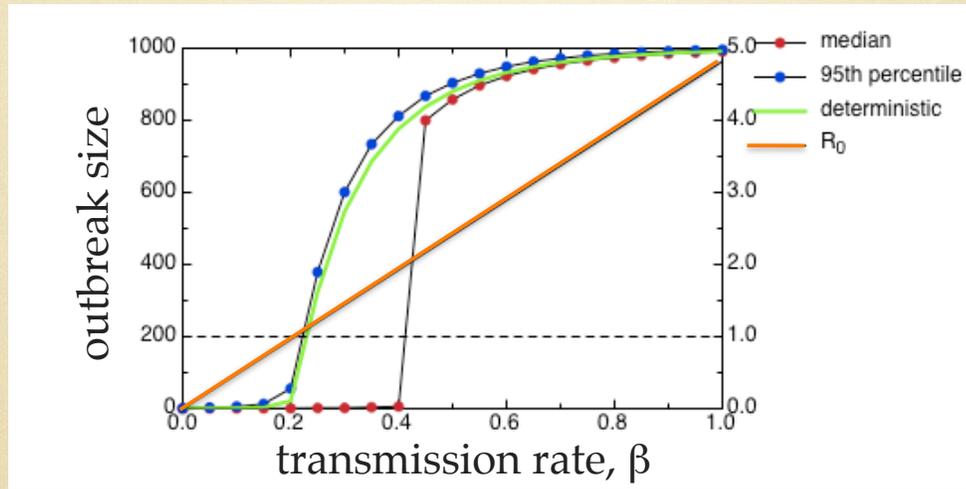


This is referred to as the J-to-U transition

Quantifying distribution

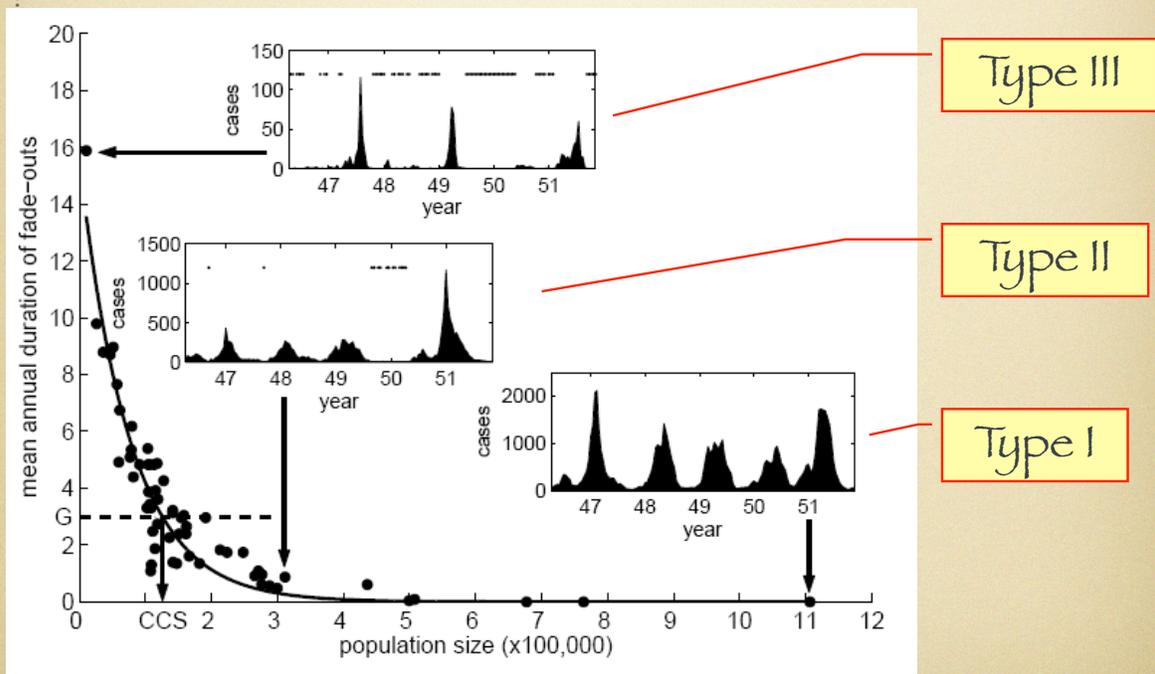


Stochastic Invasion Threshold

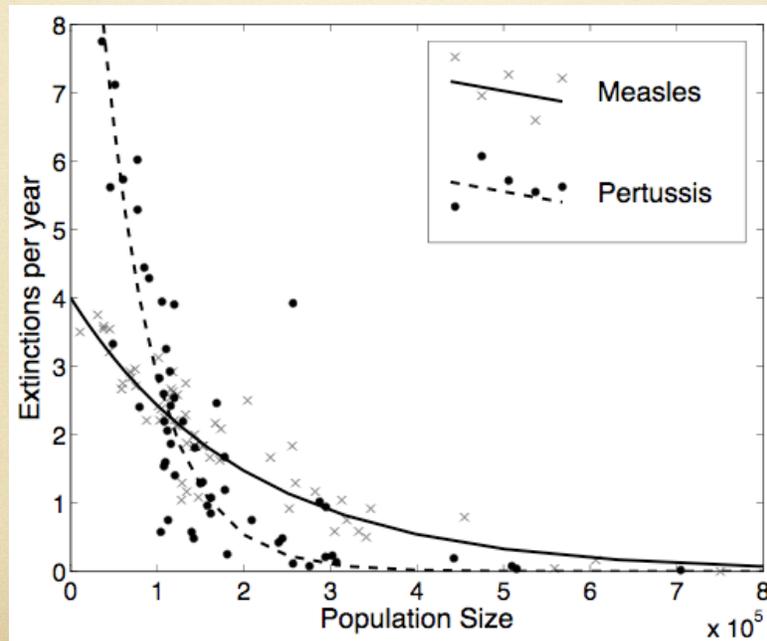


Important predictions for emerging pathogens: when R_0 only slightly above 1, "likely" outcome (median) very different from "worst-case-scenario" (95th prctile)

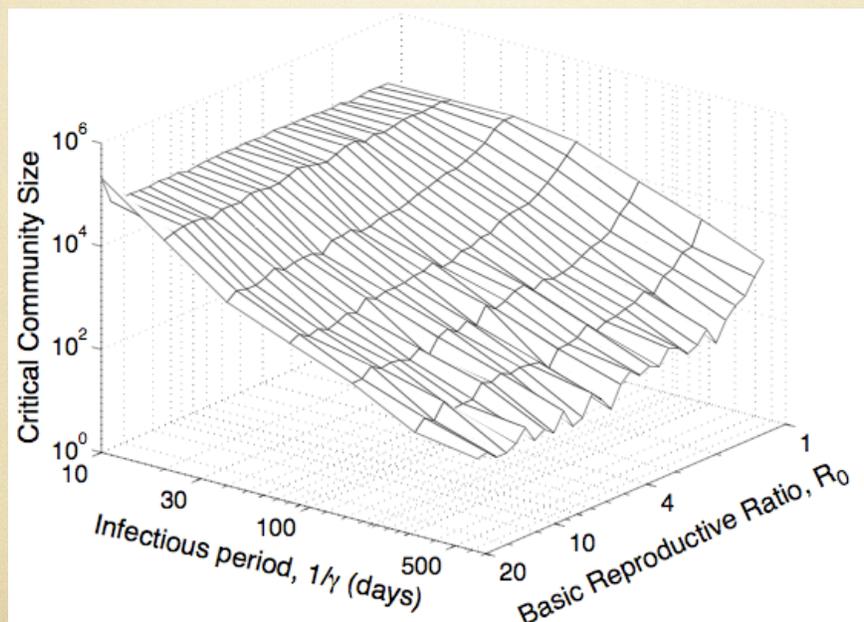
Different kinds of epidemics



Critical Community Size



Stochastic SIR simulations



Pros & Cons

- Gillespie's Direct Method has many virtues:
 - It's exact
 - Straightforward to implement
 - Widely known and used
- But it has one main drawback:
 - It's computationally costly when
 1. Population size is large
 2. There are lots of events (eg models with loss of immunity, many species etc)

Approximations

- Most commonly used approximation to GDM is so-called τ -leap method (also due to Gillespie)
- Here, system is updated at fixed time steps of length τ
- Assuming *rate* at which an event occurs is r_i , then number of times this event occurs in a small time interval τ is given by Poisson($r_i \tau$)
- [Can show GDM recovered as $\tau \rightarrow 0$]

Example

- For SIR system without demography
 - › Set parameter values and select τ
 - › Set ICs and set time = 0
 - › while time < Tmax
 - › Infections = $\text{poissrnd}(\tau * \text{beta} * X(i) * Y(i) / N)$
 - › Recovery = $\text{poissrnd}(\text{gamma} * Y(i) * \tau)$
 - › $X(i+1) = X(i) - \text{Infections}$
 - › $Y(i+1) = Y(i) + \text{Infections} - \text{Recovery}$
 - › time = time + τ
 - › end
- As $\tau \rightarrow 0$, this approximation approaches GDM
- Choice of τ is critical
 - too small and it's not much faster than GDM
 - yet too big can lead to imprecision and negative variables

Lecture Summary ...

- In reality, inferences about transmission process from data masked by 3 different kinds of noise:
observation, environmental & demographic
- Can use Gillespie's Direct Method
- Demographic noise important, especially when making predictions in settings with R_0 near 1